

DE LA RECHERCHE À L'INDUSTRIE



Paris - Saclay

www.cea.fr

AMITEX_FFT training

-

General

-

V8.17.13

-

10/10/2023

L. Gélébart

FFT-based methods

General introduction

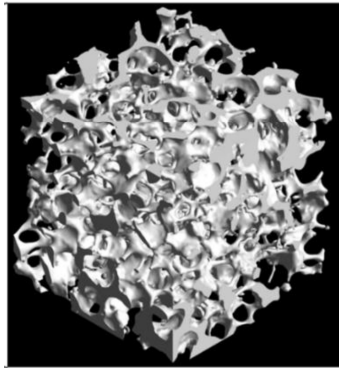
AMITEX specificities

Questions/answers in images

GENERAL INTRODUCTION

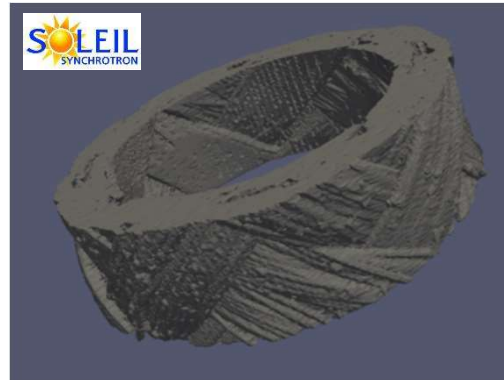
➤ Heterogeneous materials

❑ Porous ceramics



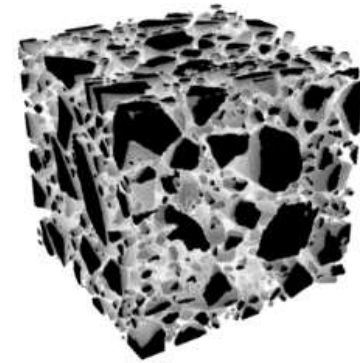
Ackermann & al. Materials 2014

❑ SiC/SiC composite tube



Thèse CHEN Y., CEA, ENPC, 2017

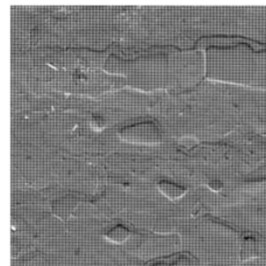
❑ Concrete



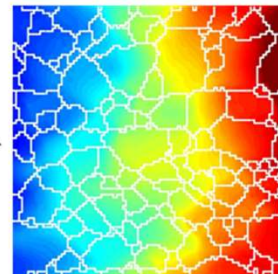
d'après F. Bernachy, CEA, 2017

❑ Polycrystals

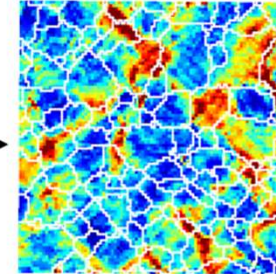
50μm



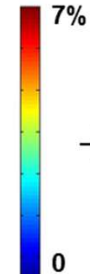
microgrille



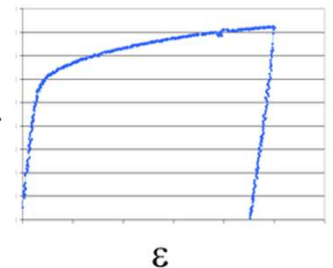
champ de
déplacement



champ de déformation
obtenu
expérimentalement



+ σ



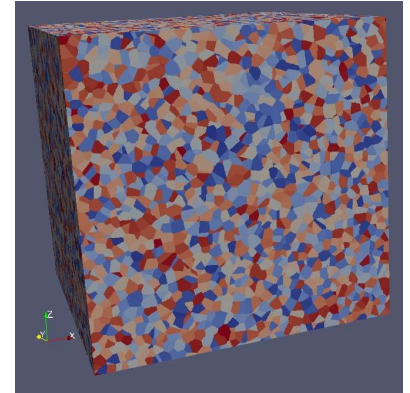
réponse mécanique
macroscopique

Thèse M. Dexet, CEA, LMS-X, 2006

GENERAL INTRODUCTION

➤ Simulation on Heterogeneous Materials

- A « Representative » Volume Element
- A Behavior law for each constituent
- An « Average » loading : uniaxial tensile test for example
- A type of Boundary Conditions : **Periodic**, often one of the best choice



➤ Natural Trends

- Increase spatial resolution (better description of local fields)
 - Increase the RVE size (representativity for complex materials)
 - More and more complex « **physically based** » behaviors
- Towards non-local, multi-physics, code coupling

➤ Standard FE solvers

- Limits are rapidly reached (computation time and size)



➤ « FFT » Solvers

- Nos tedious meshing procedure
- More efficient than FE solvers
- Well-suited for parallelism => **PUSH BACK THE LIMITS**



GENERAL INTRODUCTION

➤ FIX-POINT algorithm on LIPPMAN-SCHWINGER (Moulinec-Suquet 1994)

Problem to solve

$$\begin{aligned}\sigma(x) &= c(x) : \varepsilon(x) \\ \operatorname{div}(\sigma(x)) &= 0 \\ \langle \varepsilon(u(x)) \rangle &= E \\ &+ \text{periodicity} + \text{compatibility}\end{aligned}$$

$$\sigma(x) = c_0 : \varepsilon(x) + \underbrace{(c(x) - c_0) : \varepsilon(x)}_{\tau(x)}$$

Re-written problem

$$\begin{aligned}\sigma(x) &= c_0 : \varepsilon(x) + \tau(x) \\ \tau(x) &= (c(x) - c_0) : \varepsilon(x) \\ \operatorname{div}(\sigma(x)) &= 0 \\ \langle \varepsilon(u(x)) \rangle &= E \\ &+ \text{periodicity} + \text{compatibility}\end{aligned}$$

Auxiliary probleme

$$\begin{aligned}\sigma(x) &= c_0 : \varepsilon(x) + \tau(x) \\ \operatorname{div}(\sigma(x)) &= 0 \\ \langle \varepsilon(u(x)) \rangle &= E \\ &+ \text{periodicity} + \text{compatibility}\end{aligned}$$

Solution on auxiliary problem

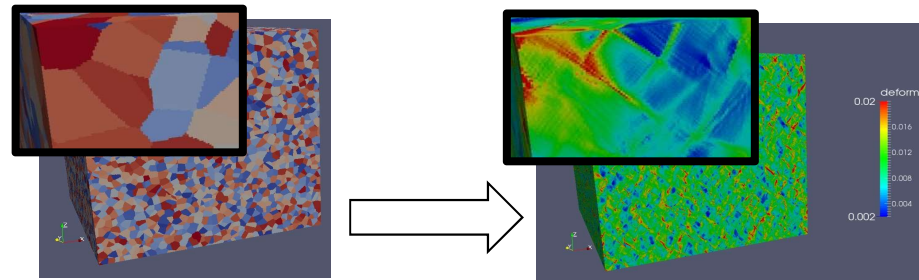
$$\varepsilon(x) = -\Gamma_0 * \tau(x) + E$$

Applying the Green operator
Simple in Fourier space (FFT)
Mura 1997

Moulinec-Suquet, 1994

$$\tau(x) = (c(x) - c_0) : \varepsilon(x)$$

AMITEX_FFTP SPECIFICITIES



- User interface
- Versatile
- Efficient
- Parallel

➤ Distributed Memory Implementation(MPI)

➤ Models

- Mechanics Finite Strains
- Mechanics Small Strains
- Diffusion

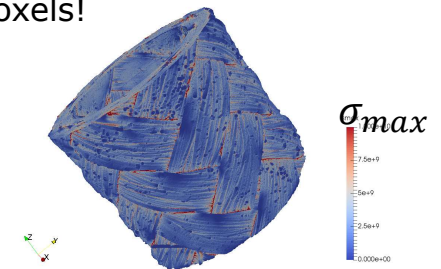
➤ Algorithm

- Fix-Point + convergence algorithm

➤ Behavior

- umat compatibility => **mfront** coupling!
- « Composite » voxels
 - Various loadings

7 Billion voxels!



AMITEX_FFTP SPECIFICITIES

➤ Distributed Memory

❑ Decomposition

✓ 1D Decomposition (slices)

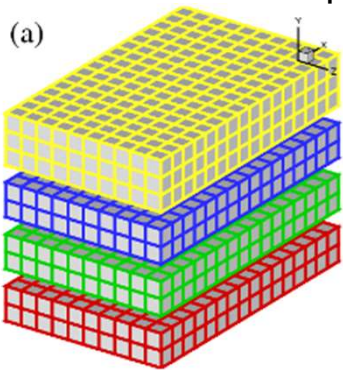


Image 1024^3

1024 processus max

Limiting for recent clusters!

✓ 2D Decomposition (pencils)

<http://www.2decomp.org/>

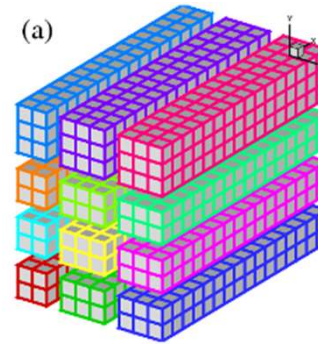


Image 1024^3

1024^2 processus max

Limit pushed back !

❑ Parallel resolution

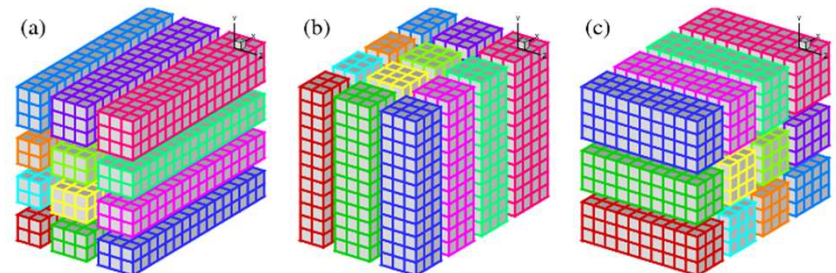
- 'Classical' // solver : local per domain + interface domain
- FFT solver : directly on the whole domain (in Fourier space)

❑ FFT 3D = succession of 1D FFT

<http://www.2decomp.org/>

Requires data transposition

- Communications (MPI_ALLTOALL)!
 - Librairie 2decomp



AMITEX_FFTP SPECIFICITIES

■ Scalability (weak)

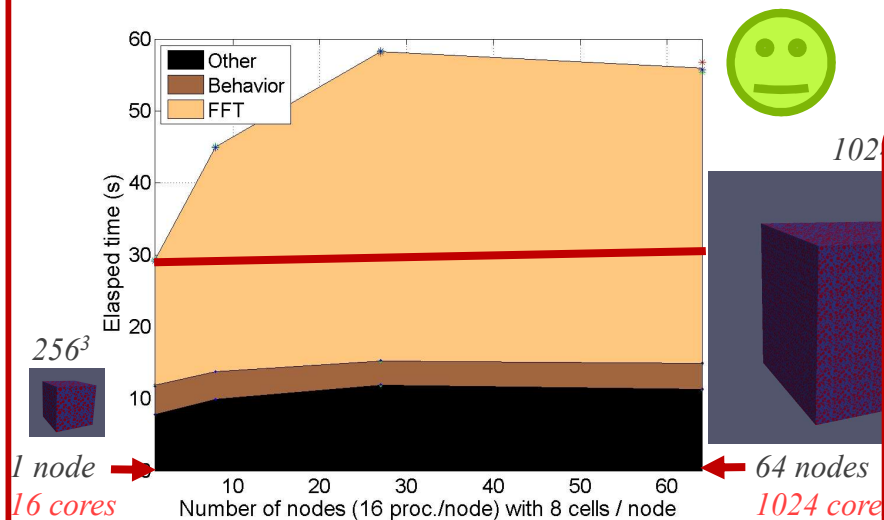
Number of nodes = N , Pb size = $N \times K0$

Time for N nodes : t_N

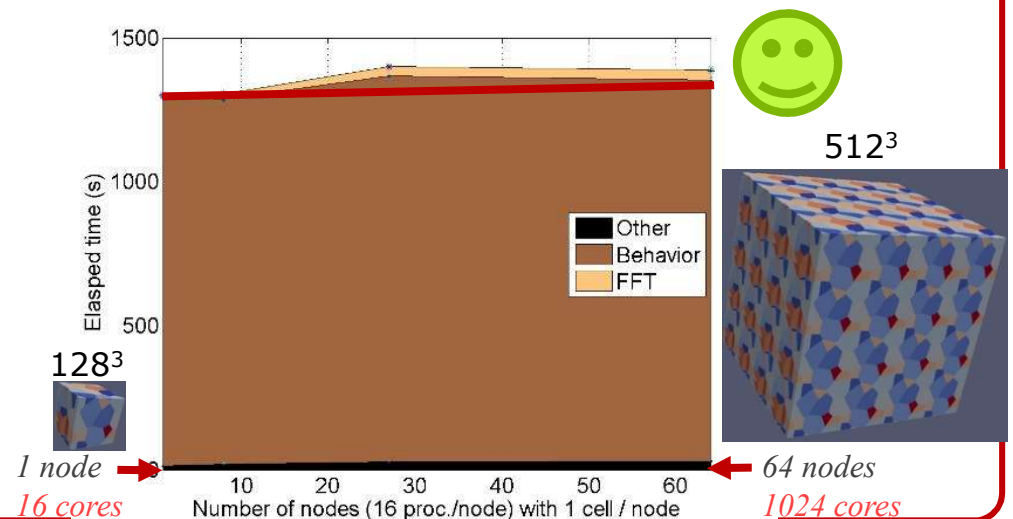
➤ Perfect scalability: $t_N = t_1$

Cluster poincare (Maison de la Simulation)
16 cores (2x8) / node sandy bridge E5-2670

“light behavior” Elasticity



“heavy behavior” Crystal plasticity



AMITEX_FFTP SPECIFICITES

➤ Extension to Finite Strains

□ HPP

$$\left\{ \begin{array}{l} \operatorname{div}(\sigma) = 0 \\ \sigma = \sigma(\nabla u^{sym}) \\ u = \overline{\nabla u^{sym}} \cdot x + u^* \\ u^* \text{ périodique} \\ \sigma \cdot n \text{ \# périodique} \end{array} \right.$$

$$\begin{array}{l} \tau = \sigma(\nabla u^{sym}) - c_0 : \nabla u^{sym} \\ \nabla u^{sym} = -\Gamma_0 * \tau + \overline{\nabla u^{sym}} \end{array}$$

□ Finite Strains

Initial configuration

$$\left\{ \begin{array}{l} \operatorname{div}(\pi) = 0 \\ \pi = \pi(\nabla u) \\ u = \overline{\nabla u} \cdot X + u^* \\ u^* \text{ périodique} \\ \pi \cdot N \text{ \# périodique} \end{array} \right.$$

$$\begin{array}{l} \tau = \pi(\nabla u) - c_0 : \nabla u \\ \nabla u = -\Gamma_0^{GT} * \tau + \overline{\nabla u} \end{array}$$

➤ IDENTICAL algorithms : UNIQUE implementation

$$\sigma \leftrightarrow \pi$$

$$\nabla u^{sym} \leftrightarrow \nabla u$$

$$\Gamma_0 \leftrightarrow \Gamma_0^{GT}$$

AMITEX_FFTP SPECIFICITIES

➤ Convergence Acceleration (© CAST3M) on the FIX-POINT algorithm

$$\begin{aligned}\tau^i &= \sigma^i - C_0 : \varepsilon^i \\ \varepsilon^{i+1} &= -\Gamma_0 * \tau^i + E\end{aligned}$$

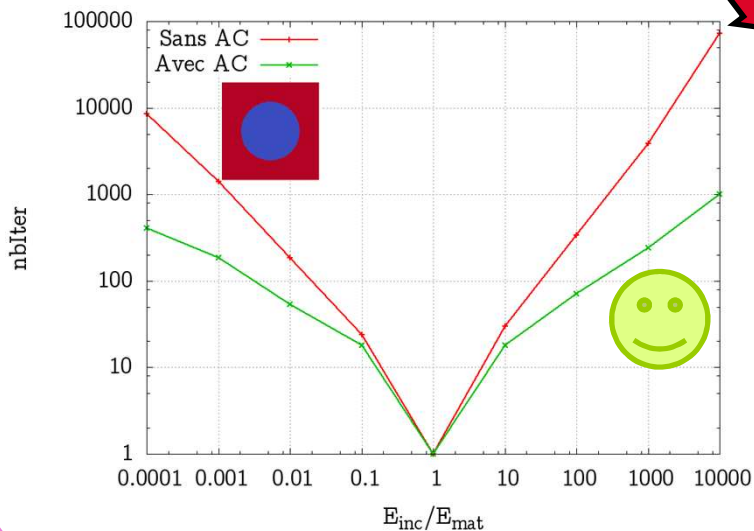
If $i + 1 \equiv 0[3]$ $\varepsilon^{i+1} = \sigma(\varepsilon^k, \varepsilon^{k+1} - \varepsilon^k \mid k = i, \dots, i - 3)$
 $\sigma^{i+1} = c(\varepsilon^{i+1})$

➤ **Memory : 4 couples** (Residual/Solution) ☹️

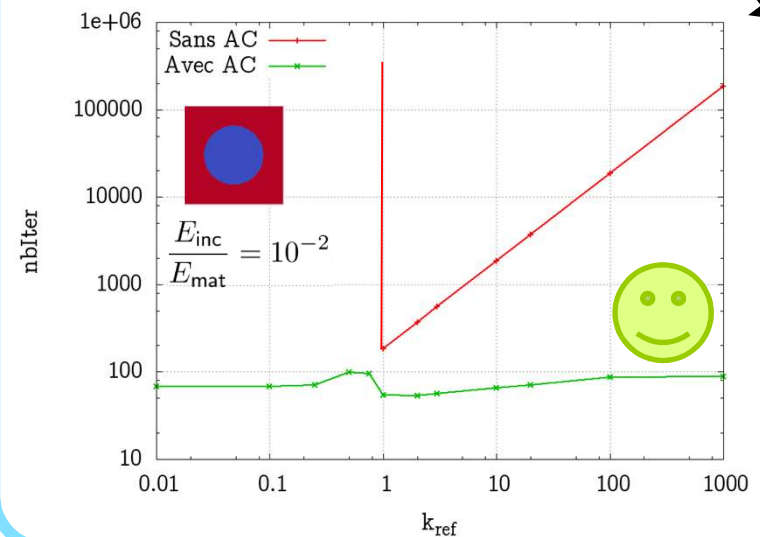
➤ **Efficiency!** 😊

➤ **No tangent behavior** to evaluate! 😊

Sensibilité au contraste mécanique



Sensibilité au Matériau de Référence



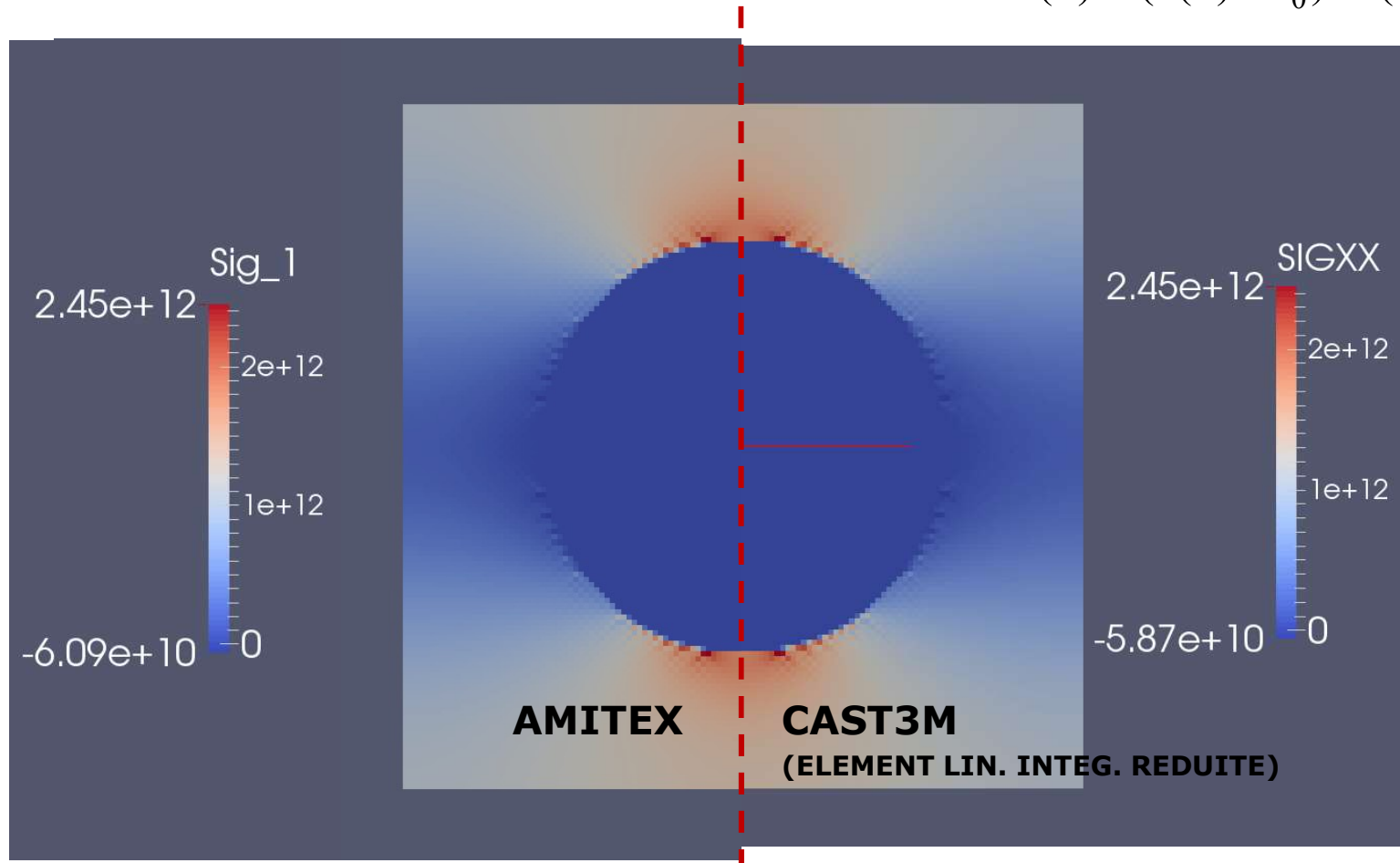
QUESTIONS – ANSWERS WITH IMAGES

■ Difference with FE or Finite Differences?

➡ **Potentially* NONE**

* : if Green operator built on FE or DF discretization

$$\begin{aligned} \varepsilon(x) &= -\Gamma_0^* \tau(x) + E \\ \tau(x) &= (c(x) - c_0) : \varepsilon(x) \end{aligned}$$



QUESTIONS – ANSWERS WITH IMAGES

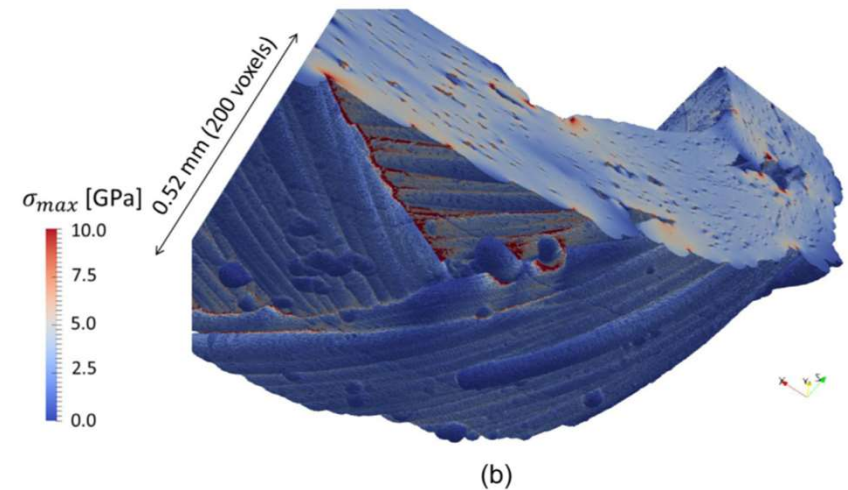
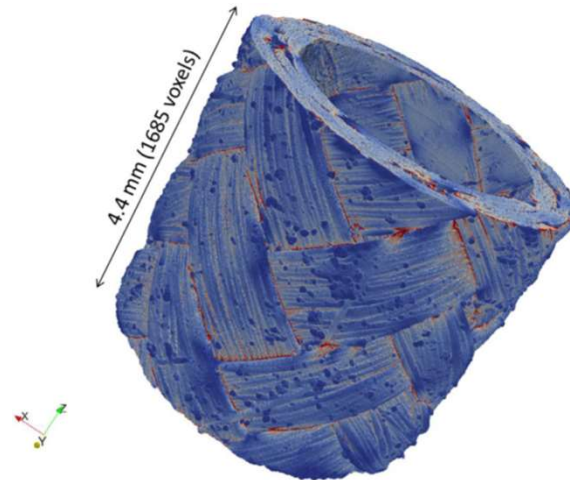
■ Beyond Periodic Boundary Conditions ?



YES

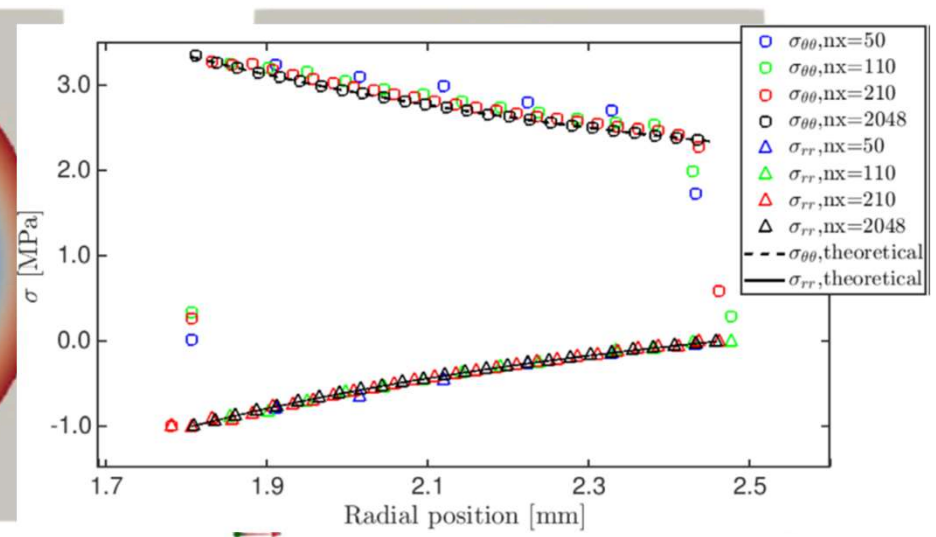
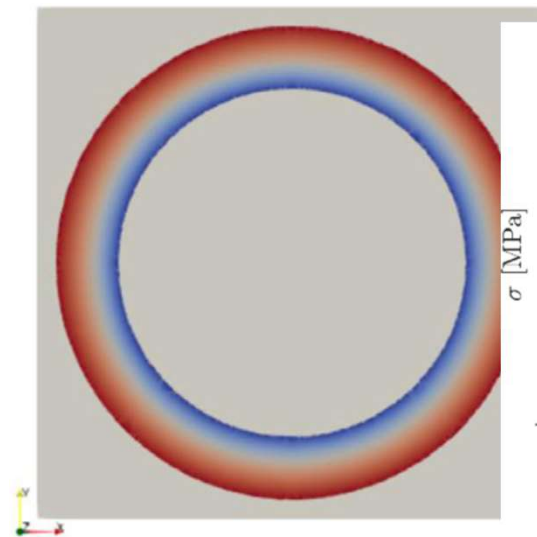
Tensile test on
SiC/SiC tube
(tomo X)

Thèse Y. Chen



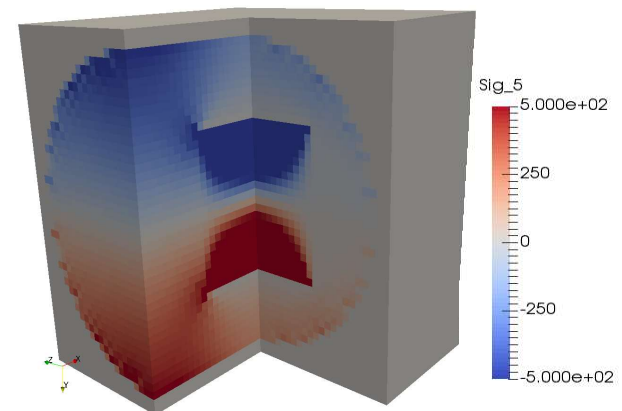
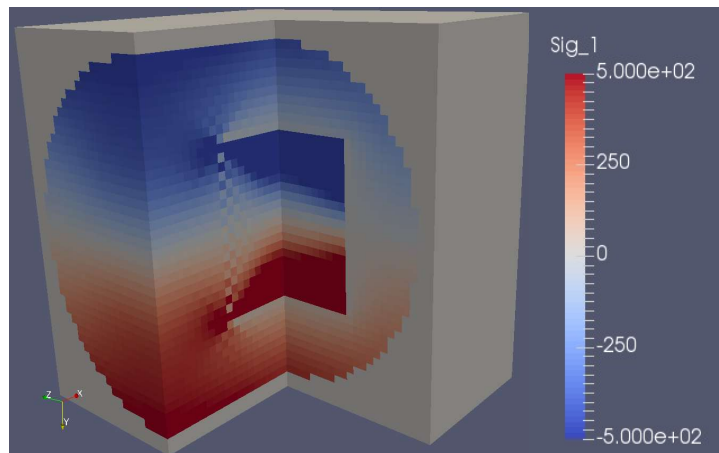
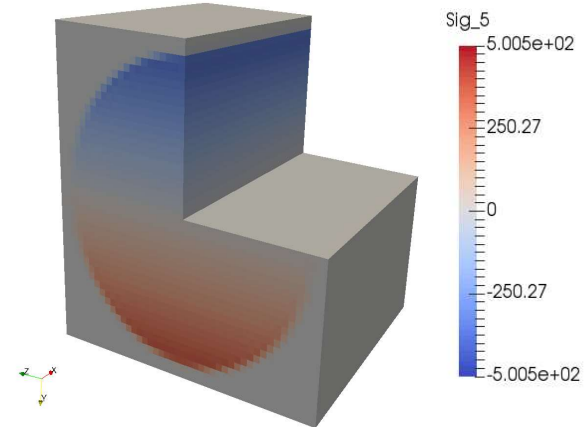
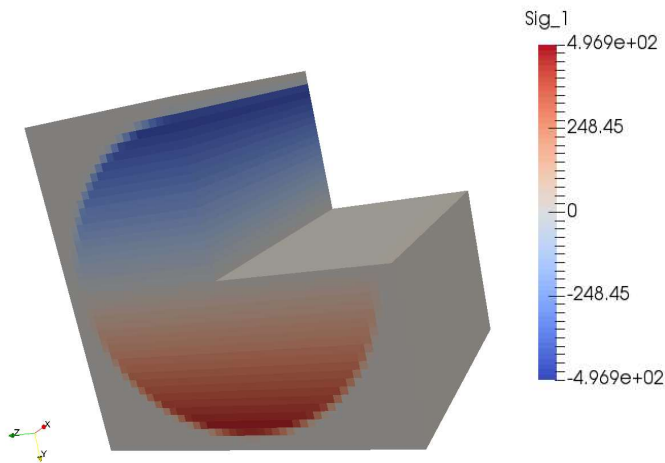
Internal pressure on
a tube

Thèse Y. Chen



QUESTIONS – ANSWERS WITH IMAGES

■ And bending, torsion of beams and plates → YES



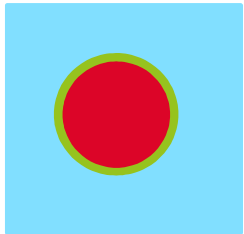
To be published...

QUESTIONS – ANSWERS WITH IMAGES

■ Stresses at interfaces ?

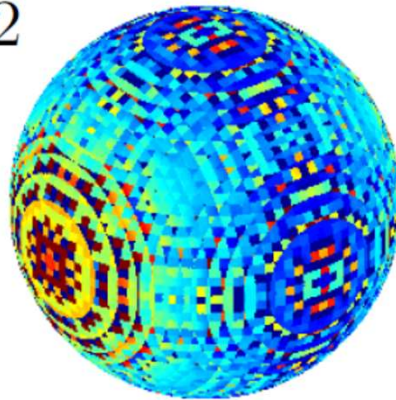
➡ YES IF, composite voxels

✓ Application to syntactic foam (PhD R. Charière)

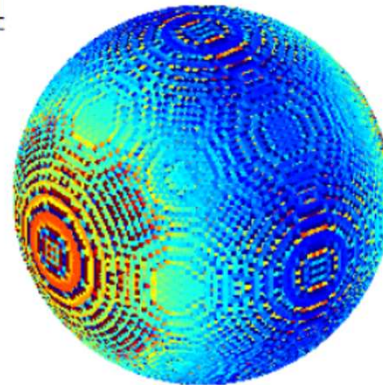


Evoid=0GPa
Eglass=69GPa
Epol=1GPa

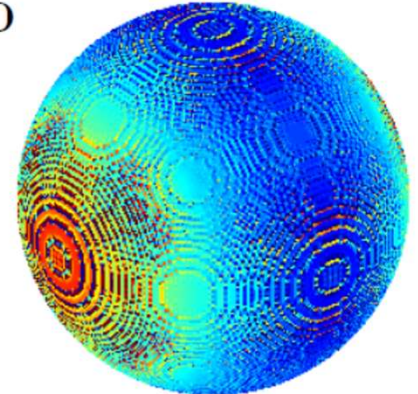
2



4

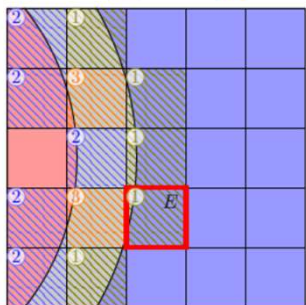


6

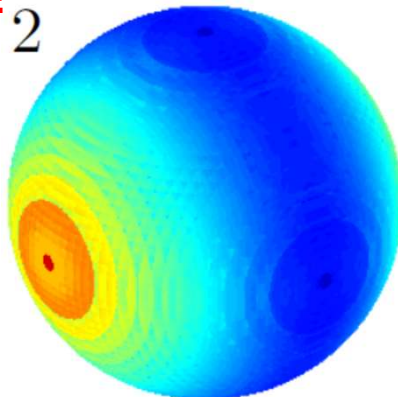


WITH COMPOSITE VOXELS

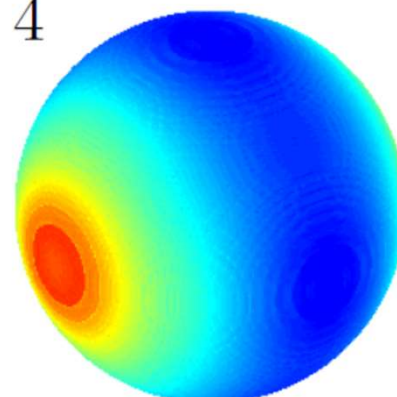
MS : MS SG : SG MSG : MSG



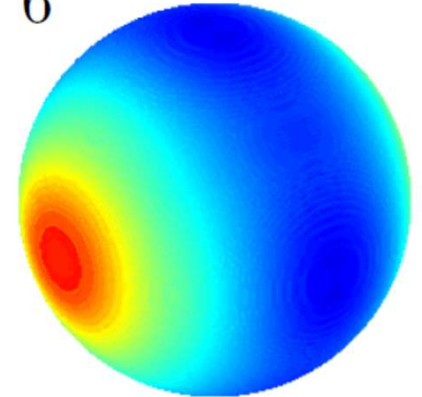
2



4



6

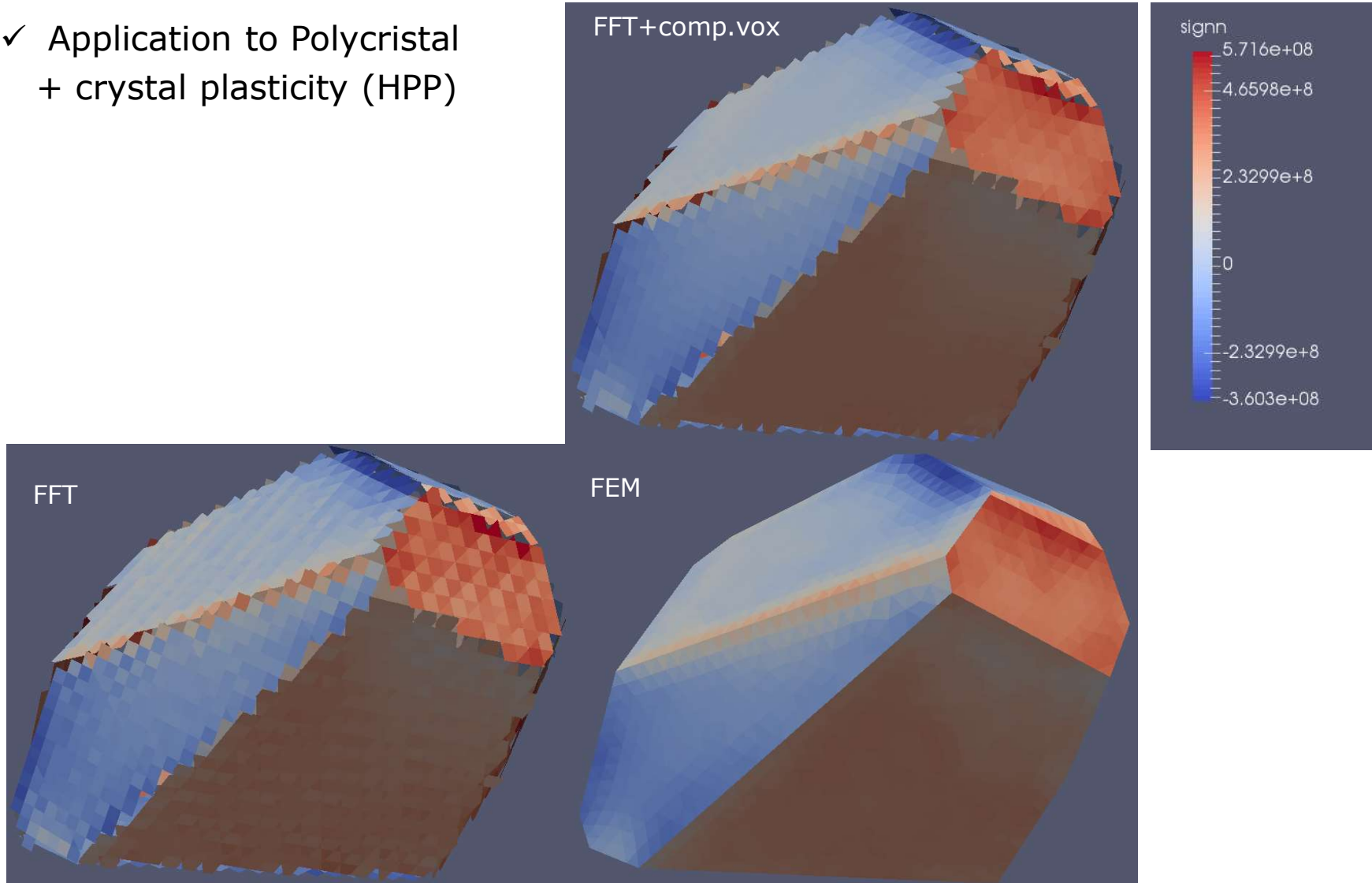


QUESTIONS – ANSWERS WITH IMAGES

■ Stresses at interfaces ?

➔ YES IF, composite voxels

- ✓ Application to Polycrystal + crystal plasticity (HPP)



VARIOUS QUESTIONS

Criteria

Average strain component	⇒	Exact (imposed)
Strain field compatibility	⇒	Exact (imposed)
Average stress component	⇒	Relative tolerance (default is 10^{-4})
Stress field equilibrium	⇒	Relative tolerance (default is 10^{-4})

Reference material Co ?

Convergence rate is affected by Co

With Convergence Acceleration the effect is lowered

A « good » choice for Co : $Xo = (\min(X) + \max(X))/2$ (with $X = \lambda$ or μ)

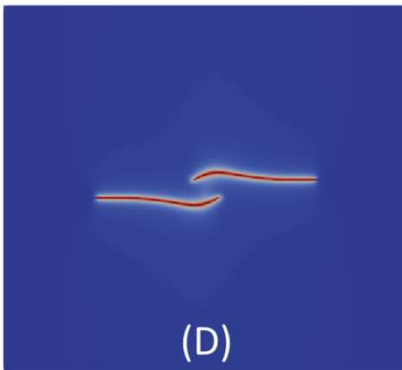
-> but in case of convergence issue, keep in mind that it can be optimized...

Solution (stress/strain fields) is not affected (up to the tolerance)

AMITEX « Extensions » for collaboration purpose

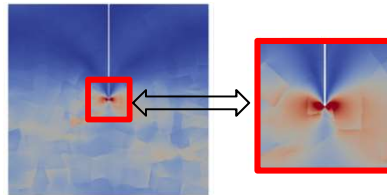
Various « Extensions » in progress...

Damage Phase Field

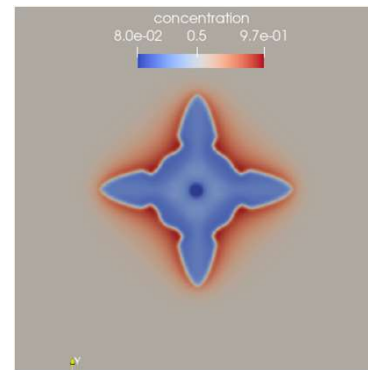


Collab. Y. Chen
(now @Bath Univ.)

Amitex Multi-Scale



Solidification



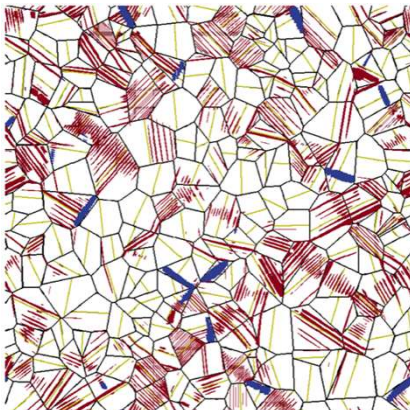
Collab, T. Pinomaa (VTT)

Solid Phase Transformation
such as $\beta \rightarrow \alpha$ in Ti, Zr...

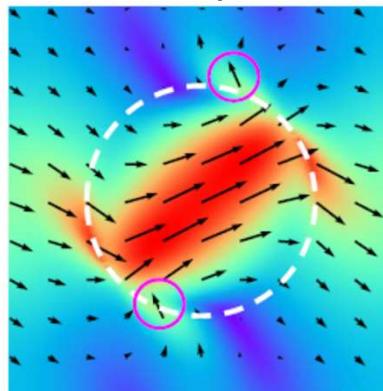


Collab J.Boisse
(LEMTA/ U. Lorraine)

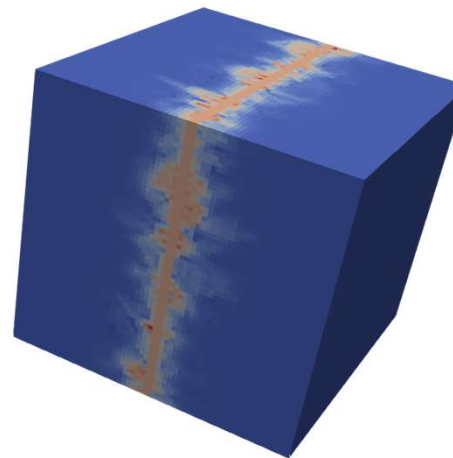
Non-local Crystal
plasticity



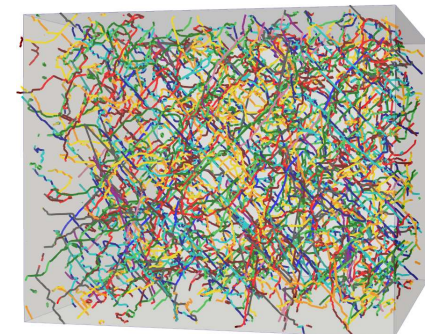
Flow in bi-porous
media (Brinkman)
Y. Chen (Bath
Univ)



Transient Thermal
Simulations



DD coupling
Micromegas (ONERA)
Numodis (CEA – L. DUPUY)



ANNEXES

➤ Parallélisme en mémoire distribuée (1)

$$\varepsilon^0(x) = E$$

$$\tau^k(x) = \sigma(\varepsilon^k(x)) - c_0 : \varepsilon^k(x)$$

$$\tau^k(x) \rightarrow \hat{\tau}^k(\xi)$$

$$\hat{\varepsilon}^{k+1}(\xi) = -\hat{\Gamma}_0(\xi) : \hat{\tau}^k(\xi) \quad \hat{\varepsilon}^{k+1}(0) = E$$

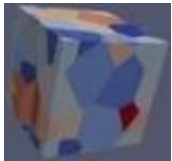
$$\hat{\varepsilon}^{k+1}(\xi) \rightarrow \varepsilon^{k+1}(x)$$

Parallélisme en
mémoire distribuée
(MPI)

- Comportement : « local » dans l'espace réel
- Opérateur de Green : « local » dans l'espace de Fourier
- FFT & iFFT : « non-local »



■ Scalabilité (2) : comportements « lourds »



- ✓ Polycrystal (voronoï), **dislocation-based Crystal Plasticity (49 var.int.)**, HPP
- ✓ Cluster poincare (Maison de la Simulation) 16 cores (2x8) / node sandy bridge E5-2670

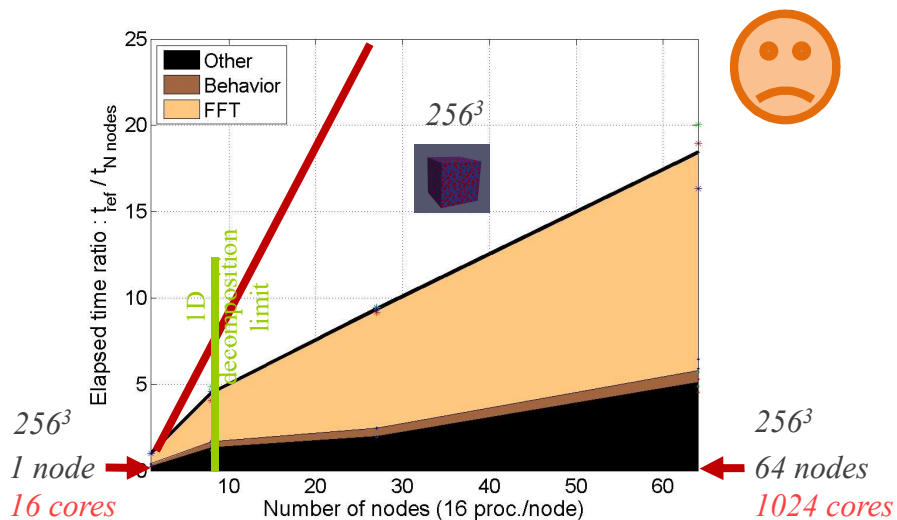
➤ Strong scalability

Number of nodes = **N**, Problem size = **K0**

Elapsed time on 1 node : t_{ref}

Elapsed time on N nodes : t_N

IDEALLY : $t_{ref} / t_N = N$



➤ Strong scalability

Number of nodes = **N**, Problem size = **K0**

Elapsed time on 1 node : t_{ref}

Elapsed time on N nodes : t_N

IDEALLY : $t_{ref} / t_N = N$

